



# A C T R I S CCRES

#### Tackling Aliasing in Doppler Radar Data: A Single-band and Dual-band De-aliasing Strategy

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## Outline

- **1. Description of the AGORA station**
- 2. Understanding Aliasing in Doppler Cloud Radars
- 3. Methodology (De-aliasing)
  - a) Mean velocity reference estimation.
    - Interactive bottom-up
    - Interpolated
    - External band
  - b) Interpolated algorithm (IPA) for single band (SB) and dual-band (DB) mode
  - c) Iterative bottom-up algorithm (IBUA)
  - d) Time continuity correction
- 4. Preliminary results
  - a) Case Study: De-aliasing of stratiform clouds
  - b) Case Study: De-aliasing of convective clouds
- 5. Validation
- 6. Concluding Remarks
- 7. Next steps

## AGORA ACTRIS CCRES station (Granada Station)



Available in CLOUDNET





Scanning capability

## RPG Dual frequency cloud radar (35,94GHz)

Sky camera Disdrometer Parsivel OTT<sup>2</sup> RPG 94-GHz Cloud radar

AGORA: Andalusian Global ObseRvatory of the Atmosphere

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#### *Case study for W-band (19/12/2024)* 2024-12-19T07:00:28 8 Height, [m] 4 7 city, [m/s] 6 6 Vmin Vmax 2 5 Range, [km] ل W-band Doppler Velo 4 3 Height, Total Height, Total Height, He 2 1 -4 07:00 07:01 07:01 07:02 07:02 07:03 07:03 07:04 07:04 07:05 -7.5 -5.0 -2.5 2.5 7.5 5.0 0.0 Time, [UTC] Doppler Velocity, [m/s]

**Understanding Aliasing in Doppler Cloud Radars** 

## Mean velocity reference estimation

**Iterative method:** use the mean Doppler velocity of the bins below (in range) as an initial estimate for the Doppler velocity of the current bin

**Interpolated method:** fill in the aliased regions by interpolating the mean Doppler velocity from nearby non-aliased regions using nearest neighbor interpolation

**External method:** use the mean Doppler velocity profile from an external band with lower frequency as an initial estimate for the Doppler velocity



### **Methodology (De-aliasing)**



ΪTR

## **Methodology (De-aliasing)**

Iterative bottom-up algorithm (IBUA) by Tuomas Siipola (CLU)

Mean computation (Vectorized phase-based estimation)

tau = 2 \* np. pi  $a = np. linspace(0, tau, n_bins, endpoint = False)$  b = np. sum(spec \* np. sin(a), axis = 1)c = np. sum(spec \* np. cos(a), axis = 1)

 $mean = (np.atan2(b,c) \% tau) / tau * n_bins$ 

Fix aliasing within chirp sequence

Shift on the circular mean at each range

Align chirp sequence

- 1. Assume not aliased at ground
- 2. Align means of the last and first ranges of adjoining chirp sequence (n Vny)





## **Time continuity correction**

SB mode may need time continuity check to dealiase convective clouds



**Inaccurate de-aliasing:** Jumps of "n x Vn", where  $n = 0, \pm 1, \pm 2$ 

#### **Correction:**

**1)** The corrected mean Doppler velocity is chosen so that the difference between the current velocity *Vm* and the reference *Vref* is minimized by adding or subtracting multiples of the Nyquist velocity.

**2)** If the velocity change exceeds one Nyquist velocity, use the dealiased Doppler velocity profile from the previous time step as the reference (*Vref*)



#### Case Study: De-aliasing under low-complexity conditions (stratiform) clouds W-band (NEBULA W) 19/12/2024



CCRES/CLU Spring Workshop, online, 19-20 May 2025

for stratiform clouds

CTRIS



## Validation *DDV*<sub>*Ka*-*W*</sub>: Methodology



(m/s), SB - IPA

DDV

DDV (m/s), DB - IPA

2.6

1.4

0.2

2.6

0.2

#### $DDV_{Ka-W}$ for each original profile and each method



## 9 days validation (Granada)



## **Concluding Remarks**

- 1. This work has successfully assessed four dealiasing algorithms:
  - Spatio-temporal continuity check
  - Case studies: stratiform and convective
- 2. Accurate dealiasing achieved with all three single-band methods for stratiform clouds.
- 3. SB mode algorithms performs quite well (IBUA is the fastest one)
- 4. In convective clouds, time continuity check improve de-aliasing performance
- 5. These are cases where the Ka-band becomes essential.
- 6. Deep convective cloud: the use of Ka-band doppler velocity spectra becomes essential



## Next steps

- Apply time continuity check to SB IBUA approach (CLU)
- Standard formulation to retrieve polarimetric variables
- Retrieving of spectral correlation coefficient and LDR (comparable to RPG LV1)
- Moments calculation



Thank you !



## **Backup slides**

## **Coherence in Range:**

**Considerations:** works quite well for most cases but can give bad results when data have **gaps** (attenuation or multilayer) or **two regimes**.



**Consequences:** Some parts of the spectra are more than one nyquist shifted in the wrong direction.

**Solution:** Baseline (something close to the truth): Ka-band or the closest profile with no folding or **correctly** de-aliased

## **Coherence in Range:**

Two

**Considerations:** works quite well for most cases but can give bad results when data have **gaps** (attenuation or multilayer) or **two regimes**.



**Consequences:** Some parts of the spectra are more than one nyquist shifted in the wrong direction.

**Solution:** Baseline (something close to the truth): Ka-band or the closest profile with no folding or correctly de-aliased



#### **Considerations:**

Two regimes:

Difficult case



**Consequences: Solution:** 

#### Ka-band as reference can also cause some minor issues due to better sensibility



**Possible solution:** range coherence verification (Difficult to know each part of the spectra is the truth)

## In general, Ka-band gives much better results in complicated cases

