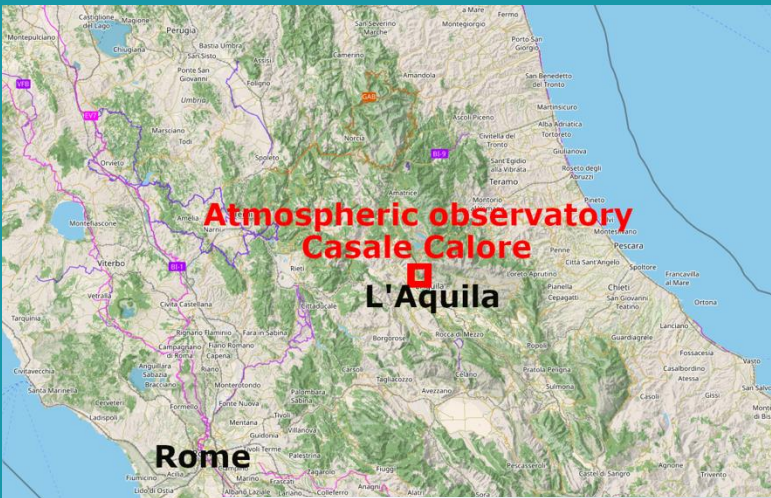


L'Aquila NF (AQ-NF)



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Analysis of in-cloud vertical air velocity from W-band radar

Opportunity for a routine product?

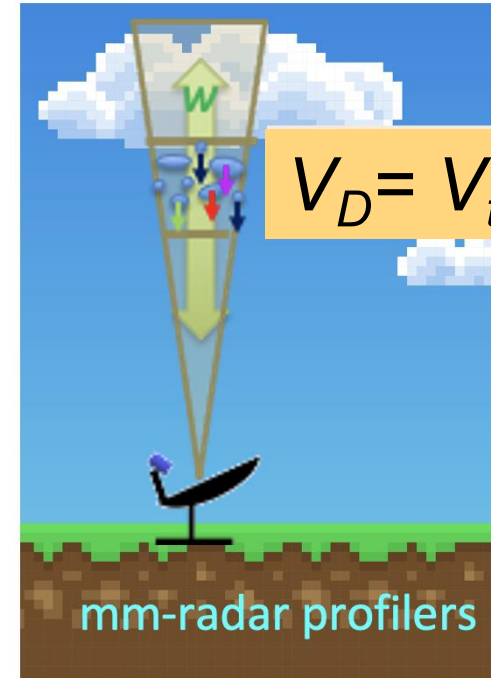
Mario Montopoli and Saverio Di Fabio
and support from AQ-NF team
(mario.montopoli@cnr.it)

CCRES/CLU Autumn Workshop, Evora, 22 October 2025

GOAL

- Disentangle terminal velocity (V_t) from vertical air velocity (w) in rain regimes

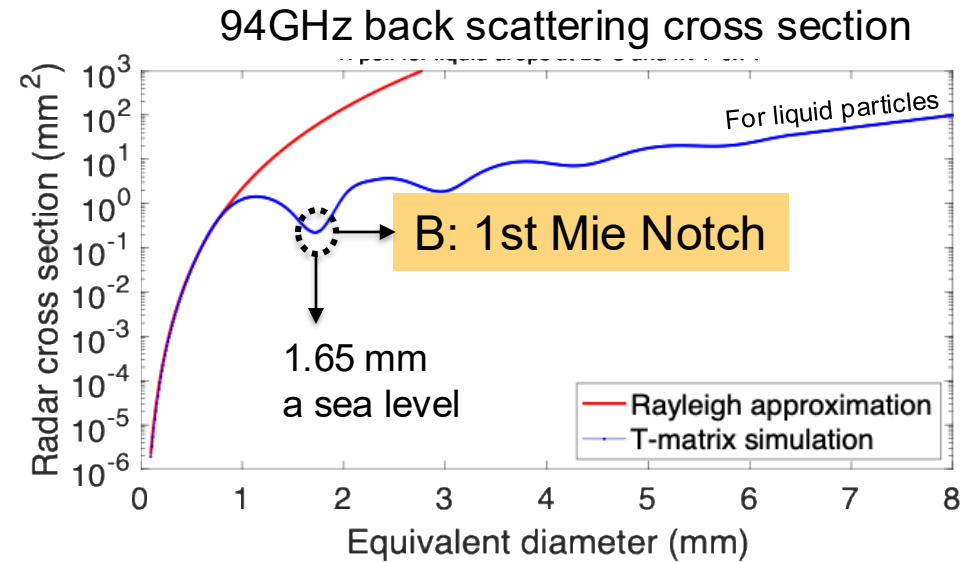
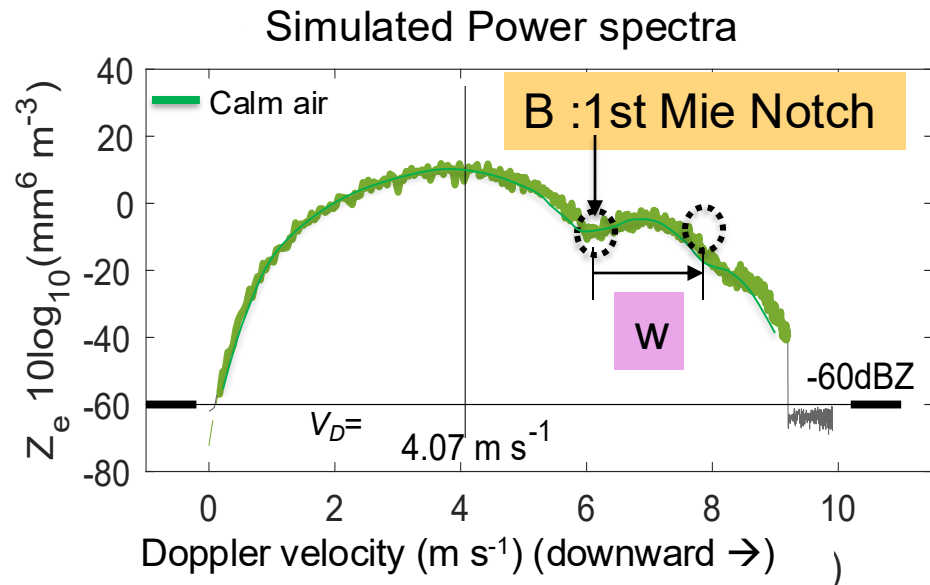
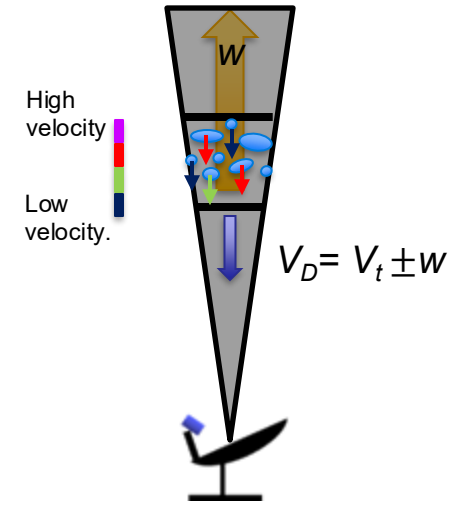
$w = ?$



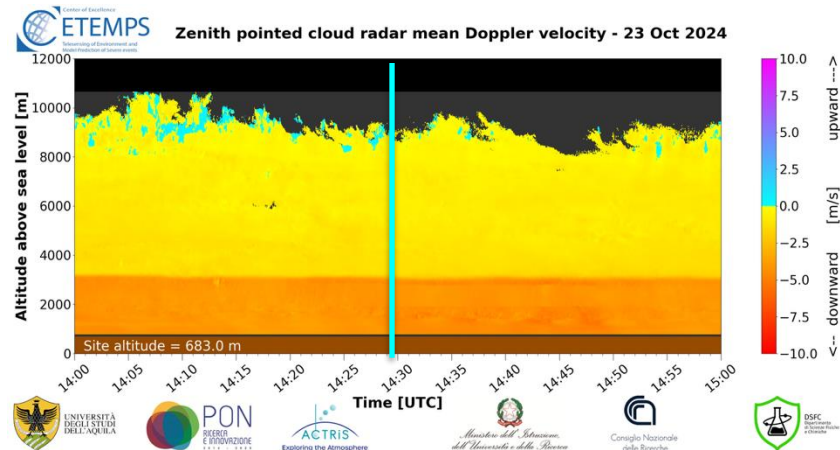
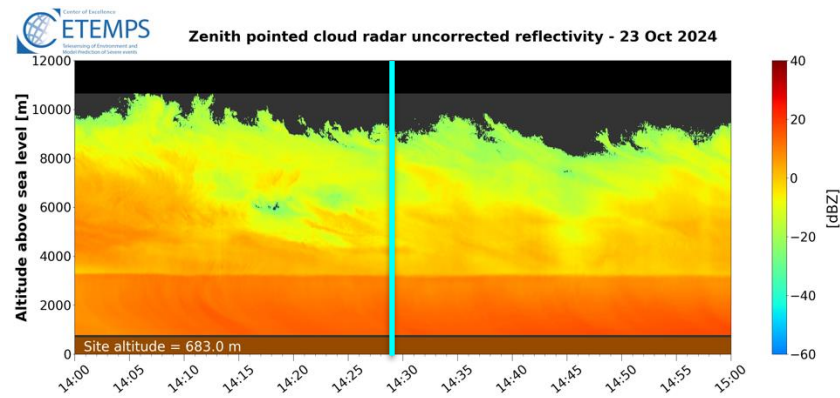
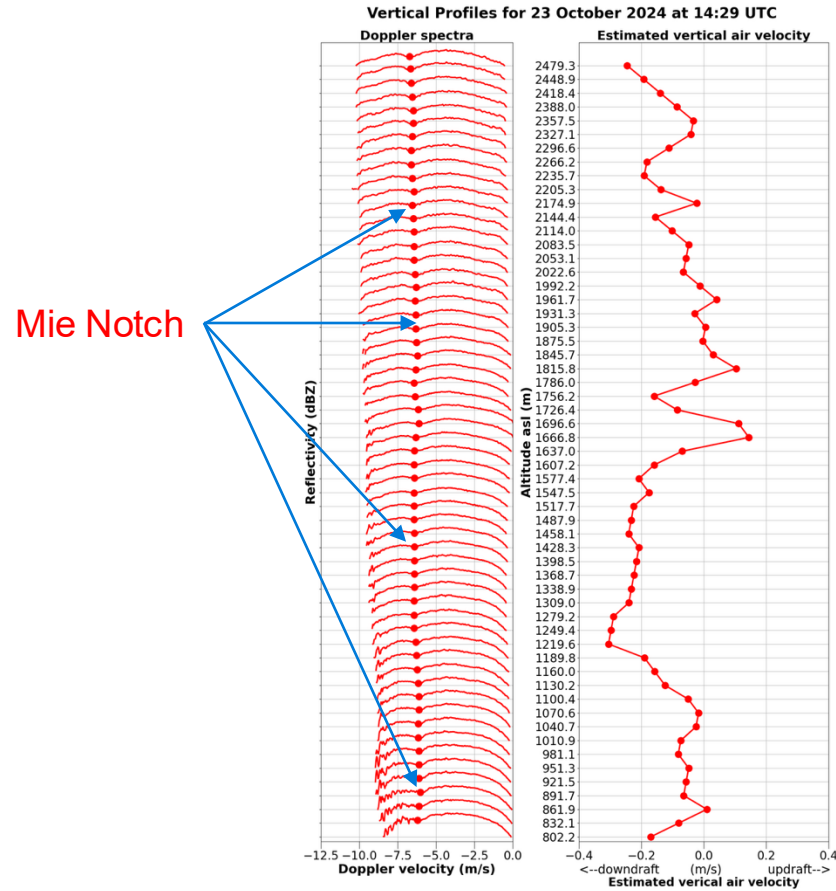
$$V_D = V_t + w$$

METHODS

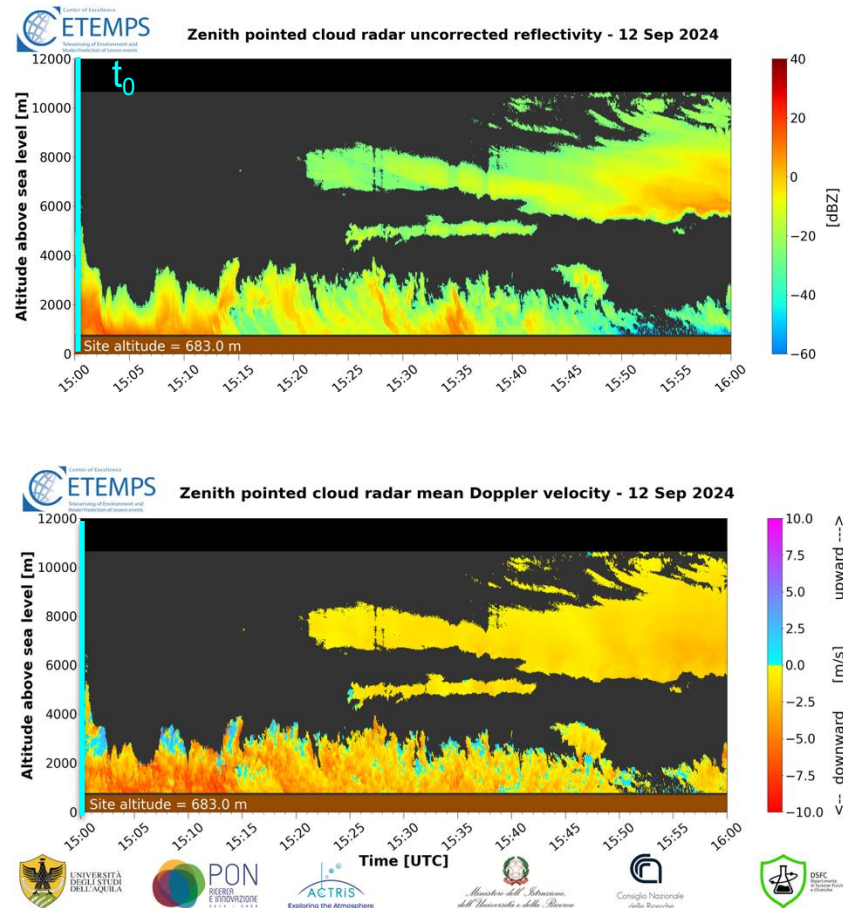
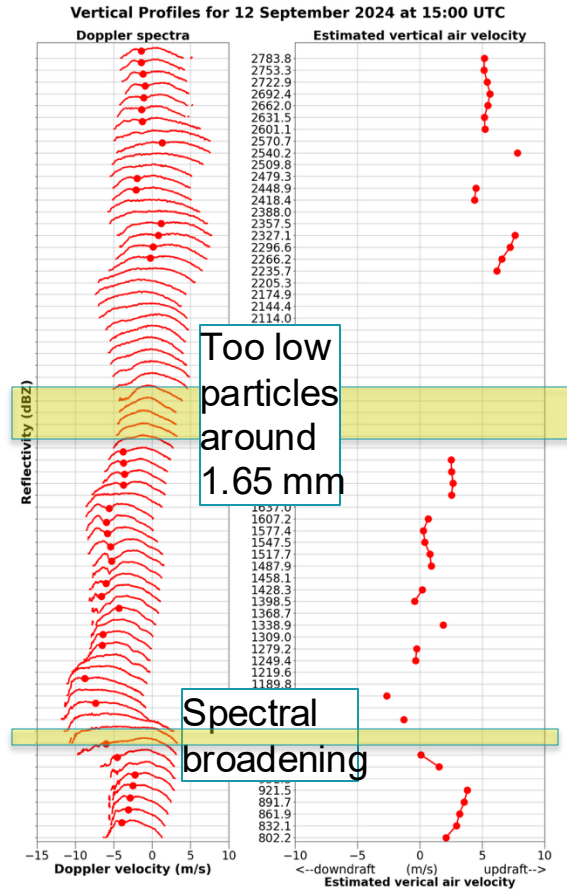
- Use Mie Notch technique (*Kollias et al., 2002*) to directly estimated w from 94GHz vertically pointing radar
- Tune $V_t = a Z^b$ using $V_t = V_D - w$ with V_D , Z measured by the 94GHz radar



Vertical air estimation: a stratiform example



Vertical air estimation: a convective example



Mie notch is not always detectable, so vertical air profile may result incomplete especially in convection

Statistic of vertical air wind detectability

- Initial **373831** total number of range bins processed (the dataset is mostly stratiform!!!)
- After a screening procedure on each power spectrum we got:
- **111751 (29.9%)** of range bins for which we were able to detect Mie Notch (i.e. vertical air, w)
- Thus, we used Mie notch w to obtain a target $V_t = V_D - w$ and tune a $\hat{V}_t = a Z^b$ relationship to achieve an indirect estimate of vertical air as $w = V_D - \hat{V}_t$ which is expected to be more likely available along the profile.

see next slide



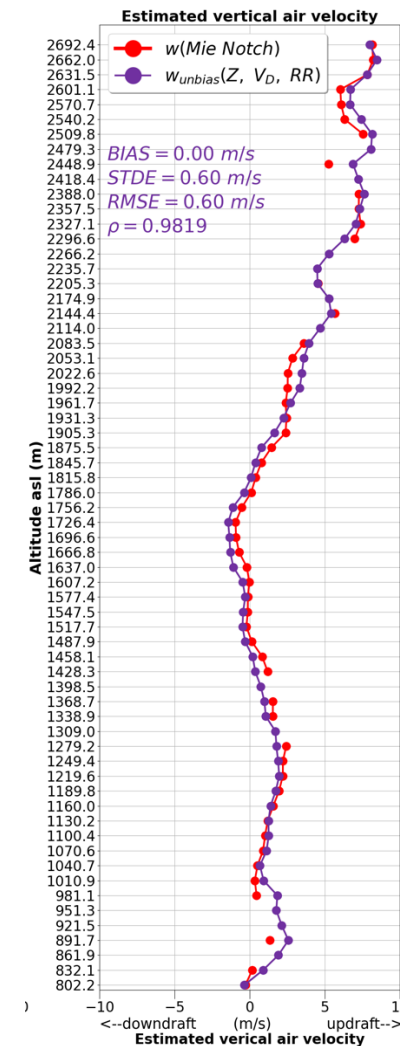
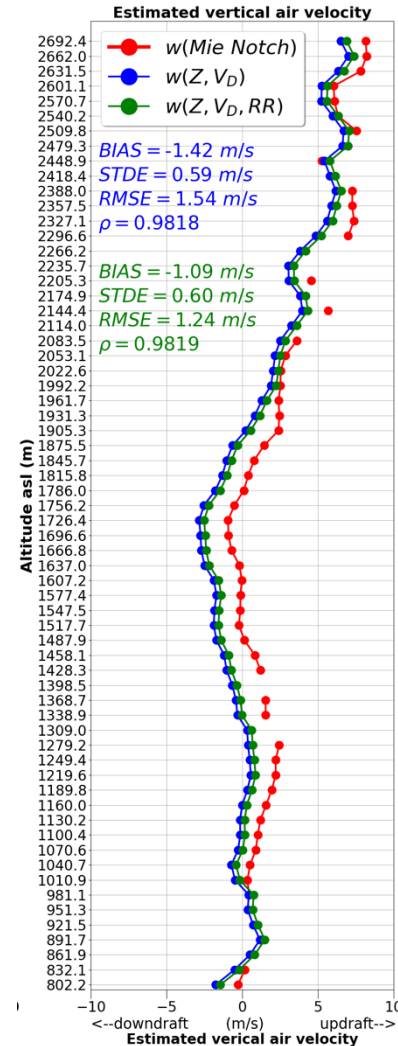
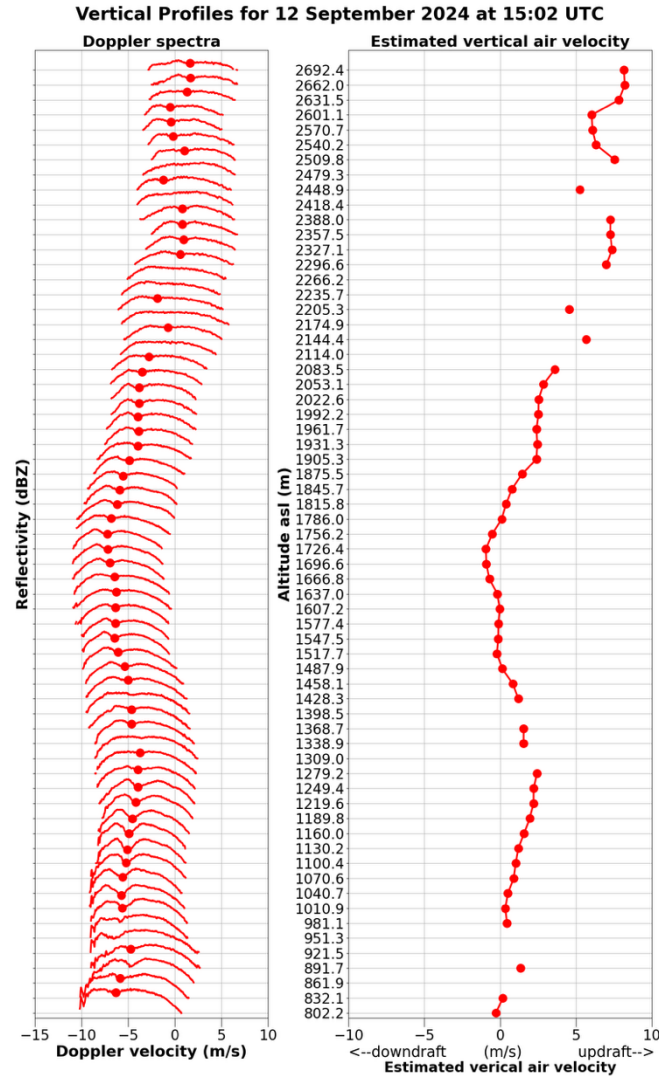
Example of vertical air wind profiles

$w(\text{MieNotch})$

$$w(Z, V_D, RR) = V_D - \underbrace{a(RR)Z^{b(RR)}}_{\hat{V}_t}$$

$$w_{\text{unbiased}}(Z, V_D, RR) = w - \text{bias}$$

$$\text{bias} = \langle w(Z, V_D, RR) \rangle_h - \langle w(\text{MieNotch}) \rangle_h$$



Vertical air wind from Z, V_D, RR

- When we compare $w(\text{MieNotch})$ and $w_{\text{unbiased}}(Z, V_D, RR)$ we obtain an excellent agreement.
- However, the tune of $w_{\text{unbiased}}(Z, V_D, RR)$ is performed on the same dataset used for testing. So a more fair comparison should be extended to an independent dataset

$$\hat{V}_t = a(RR)Z^{b(RR)}$$

$$w(Z, V_D, RR) = V_D - \hat{V}_t$$

$$\text{bias} = \langle w(Z, V_D, RR) \rangle_h - \langle w(\text{MieNotch}) \rangle_h$$

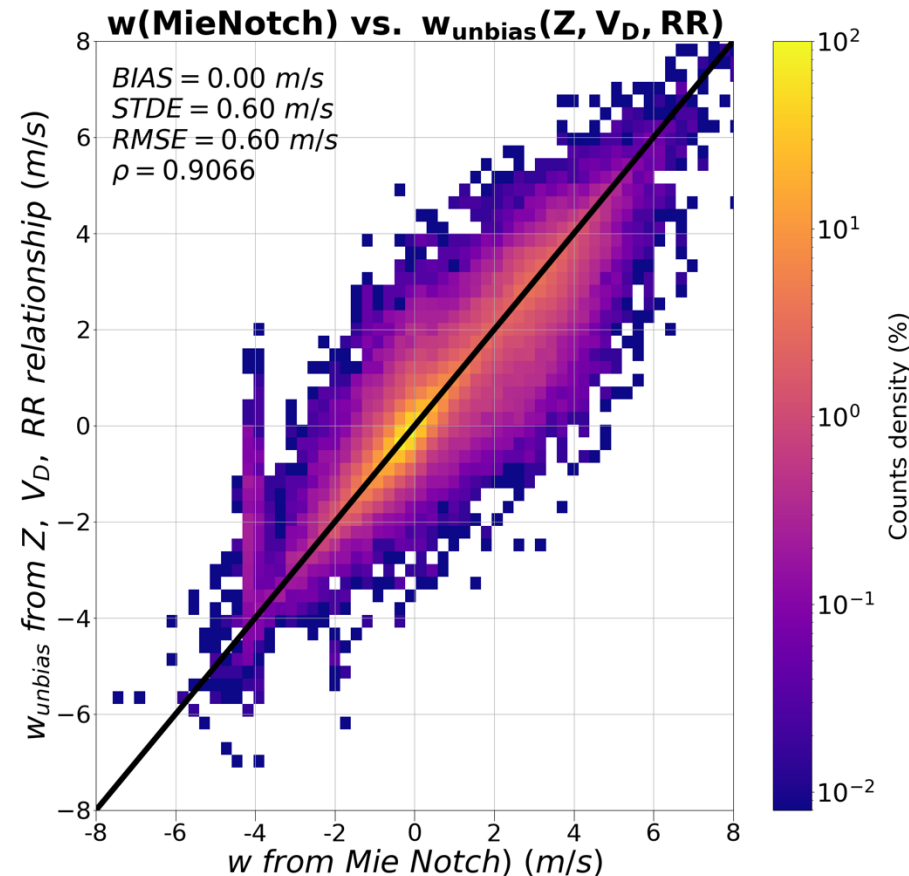
$$w_{\text{unbiased}}(Z, V_D, RR) = w - \text{bias}$$

RR : rain rate at the ground from LPM disdrometer

$\langle \cdot \rangle_h$: average operator along the profiles

Z : bias corrected equivalent reflectivity factor

V_D : vertical Doppler velocity



Future steps

- **Extends dataset**
- **Path attenuation compensation**

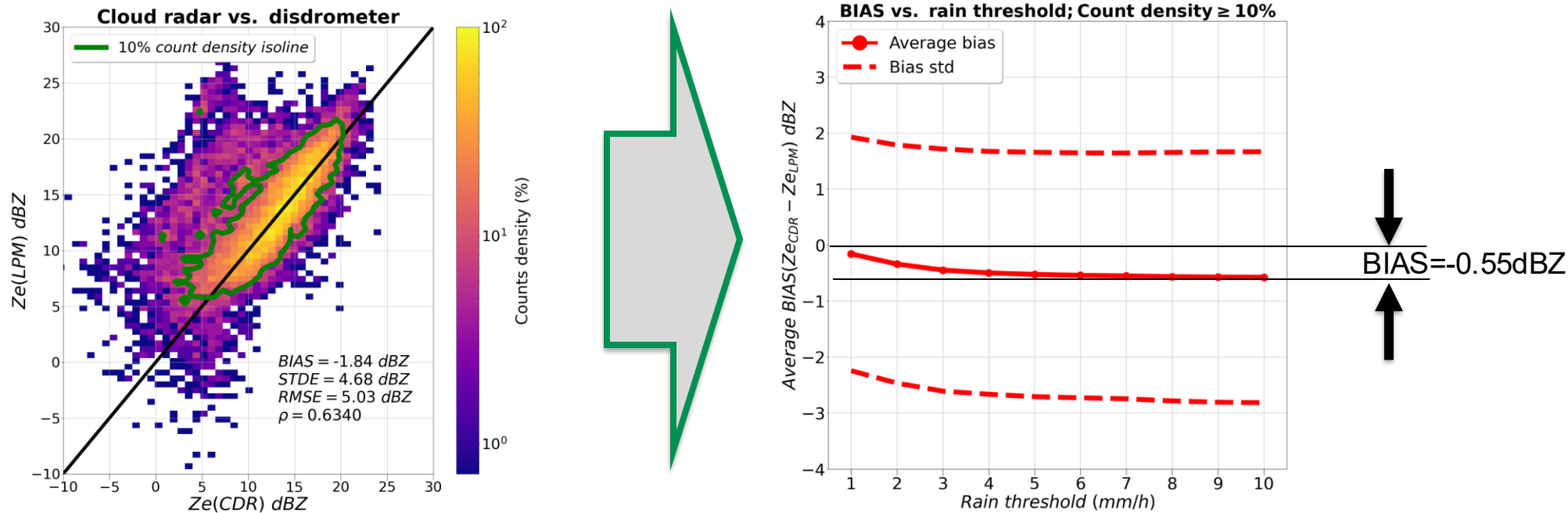


Thank you !

backup

RADAR CALIBRATION

- Z_e radar (CDR) vs Z_e disdrometer (LPM) 373831 total number of range bins collected
- 1st bin at 120 m a.g.l.
- At least 5 min of continuous rain periods are selected within $0.1 < R < 300$ mm/h
- Scatter density larger than 10% is used to exclude tails of the Z_e distribution
- Rain rates from LPM is varied between 0.1 and 10 mm/h to look at the regimes where BIAS stabilise.



Z_e radar (CDR) is compensated by 0.55 dBZ of bias.